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3D Printed Robot Arm

Objectives

* Develop software to maneuver robot arm. Robot arm should lift a ball, and then place it in a specific location

Materials

* Arduino Uno/Nano
* 3D printed Parts
* Arduino IDE
* NetBeans IDE
  + Scene Builder
* Servos
* Nuts/Bolts
* Circuit Board
* Wires
* Breadboard
* Misc. Materials

Steps

1. Research different methods to control Arduino from desktop